

Mission 6 Review Kahoot Questions

<p>A servo has all the following except one. Which ONE is NOT part of a servo?</p>	<ul style="list-style-type: none"> a. A CD motor and gearbox b. Speaker c. A controller circuit d. An internal feedback mechanism
<p>Which statement about a “finite-state machine” is FALSE?</p>	<ul style="list-style-type: none"> a. It is the status of a system with transitions. b. It means your program can only be in one state at a given time. c. “Finite” means an unlimited amount of possibilities. d. Usually “state” is based on variables in your code.
<p>Which statement about “state” is FALSE?</p>	<ul style="list-style-type: none"> a. A state is required for the code to run. b. A state is a phase of a program. c. Keeping track of states helps you manage your code. d. Each state might have its own set of conditions it is tracking.
<p>Which statement about “transition” is FALSE?</p>	<ul style="list-style-type: none"> a. A transition is moving between states. b. A transition moves the program from one state to another. c. A transition happens when a condition is met. d. A transition is optional in a finite-state machine.
<p>Which peripheral can rotate continuously forward and backward?</p>	<ul style="list-style-type: none"> a. Potentiometer b. 360 servo c. 180 servo d. Divider board
<p>Which peripheral moves to a specified position and holds its place?</p>	<ul style="list-style-type: none"> a. Potentiometer b. 360 servo c. 180 servo d. Divider board
<p>Which of the statements about the 360 servo is FALSE?</p>	<ul style="list-style-type: none"> a. It rotates faster with a higher cycle percentage. b. It has continuous rotation. c. It has no sense of position. d. It rotates forward and backward.
<p>What signal is required to operate a servo?</p>	<ul style="list-style-type: none"> a. Voltage b. Analog PWM c. True or False value d. Digital PWM
<p>What code sets up the servo?</p>	<ul style="list-style-type: none"> a. <code>fan = exp.pwm_in(exp.PORT0, frequency=2)</code> b. <code>fan = exp.analog_out(exp.PORT0, frequency=PERIOD)</code> c. <code>fan = exp.digital_out(exp.PORT0, frequency=2)</code> d. <code>fan = exp.pwm_out(exp.PORT0, frequency=PERIOD)</code>
<p>Evaluate the expression: <code>12 // 10</code></p>	<ul style="list-style-type: none"> a. 1.2 b. 1 c. 2 d. .83
<p>Evaluate the expression: <code>7 // 4</code></p>	<ul style="list-style-type: none"> a. 1.75 b. 1 c. 2 d. .75

Given this percentage of the cycle, which direction will a 360 servo rotate? 60%	<ul style="list-style-type: none">a. Forwardb. Stoppedc. Backwardd. Depends on the state
Given this percentage of the cycle, which direction will a 360 servo rotate? 20%	<ul style="list-style-type: none">a. Forwardb. Stoppedc. Backwardd. Depends on the state
Given this percentage of the cycle, which direction will a 360 servo rotate? 80%	<ul style="list-style-type: none">a. Forwardb. Stoppedc. Backwardd. Depends on the state
This code is an example of: <pre>while True: if state == "maintenance": if switch.value == POWER_ON: fan.duty_cycle = set_servo(FORWARD) state = 'active' elif state == "active": if switch.value == POWER_OFF: fan.duty_cycle = set_servo(STOP) state = 'maintenance'</pre>	<ul style="list-style-type: none">a. A compound conditionb. Setting up a peripheralc. Using REPLd. A finite-state machine